AMENDMENTS TO THE SPECIFICATION

Please amend paragraph 21 to replace "7B" with "7C" as shown in the amended paragraph below:

[0021] FIG. 7C ~~7B~~ is an edge view of the side plate insert utilized to secure the transaxle to the side plate according to the present invention.

Please insert the following brief descriptions of FIGS. 13A and 13B between paragraphs 0034 and 0035:

[0034A] FIG. 13A is a side view of the hub in a first hub position.
[0034B] FIG. 13B is a side view of the hub in a second hub position.

Please amend paragraph 0040 to replace "convertible frame 26" with convertible frame 24" as shown in the following amended paragraph:

[0040] An example of a prior art hand truck 10 is shown in side view in FIG. 1A, and in front view in FIG. 1B. Such hand truck comprises a first frame 12a, hand truck wheels 14, and a nose 16. Such hand truck 10 is useful for moving objects which may be balanced on the nose 16. An example of a prior art convertible hand truck 20 is shown in side view in FIG. 2A, and in front view in FIG. 2B, and is further shown in FIG. 3 converted from a hand truck to a platform. The convertible hand truck 20 comprises a second frame 12b, the hand truck wheels 16, the nose 16, and additionally, caster wheels 22 supported by convertible frame 24, handles 26 mounted on the convertible frame 24, a latching member 28 attached to the convertible frame 24 ~~26~~ proximal to the caster wheels 22, pivot/slide member 30 slidably cooperating with the convertible frame 24, and a latch receiving member 32 attached to the frame 12b and adapted to cooperate with the latching member 28.

Please amend paragraph 0046 to append "A side plate brace 38b runs between side plates 38" to the end of the original paragraph 0046 as shown in the following amended paragraph:

[0046] The internal components of the powering assembly 34 are shown in FIG. 8, and in cross-sectional views in FIGS. 8A, 8B, and 8C taken along lines 8A - 8A, 8B - 8B, and 8C - 8C of FIG. 8 respectively. The powering assembly 34 includes as major components an electric motor 42, a power source 46, a programable motor controller 44, a recharger 48, and a transaxle 40. The transaxle 40 includes a differential 40a which differentially connects right and left axles, thereby allowing easy maneuvering (e.g., turning) of the hand truck. The major components reside between side plates 38 and behind back plate 37. An electrical receptacle 54 resides in the left one of the side plates 38. A side plate brace 38b runs between side plates 38.

Please amend paragraph 0052 to replace "display 50" with "display 60" in three places, and please replace "door 56" with "door 58", as shown in the amended paragraph 0052 below:

[0052] A controller display 60 ~~50~~ and on/off switch 62 reside above a right power source door 58 ~~56~~ shown in FIG. 8C. The controller display displays diagnostic information upon turn-on, preferably for three seconds. The display 60 ~~50~~ provides information regarding brake and speed controls, and any other faults (i.e., wiring etc.) and is generated by the motor controller 44 software. After the initial display of diagnostic information, the display 60 ~~50~~ provides power source 46 level.

Please amend paragraph 0053 to replace "handle 36" with "handle 26" as shown in the following amended paragraph:

[0053] A detained view of the handle 26 (generally the right handle) is shown in FIG. 9. The speed control 36, the hi/low speed switch 36a, and an indicator 64 reside on the handle 26 ~~36~~. The speed control 36 is a finger control (wig-wag) type switch. The switch 36 preferably has as much as approximately ± forty five degrees of motion and more preferably has approximately ± fifteen degrees of motion, and provides both forward and rearward motion. The switch 36 preferably provides a range of forward and reverse speed based on the amount the switch 36 vis moved, and is more preferably a potentiometer, and most preferably a Model No. J3R-I-5K potentiometer made by Sakea Tsushin Kogyo Co., LTD. in Kawasaki-City, Japan. The motor controller 44 automatically determines trim for the control 36 exercising the motor controller software.